

Pixel-Grounded Prototypical Part Networks

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Background

AI has a trustworthiness problem.

Rent Going Up? One Company's Algorithm Could Be Why.

by Heather Vogell, ProPublica, with data analysis by Haru Coryno, ProPublica, and Ryan Little



IBM's Watson supercomputer recommended 'unsafe and incorrect' cancer treatments, internal documents show

Amazon's Face Recognition Falsely Matched 28 Members of Congress With Mugshots

Wrongfully Accused by an Algorithm

In what may be the first known case of its kind, a faulty facial recognition match led to a Michigan man's arrest for a crime he did not commit.

People that say that AI will take over the world:

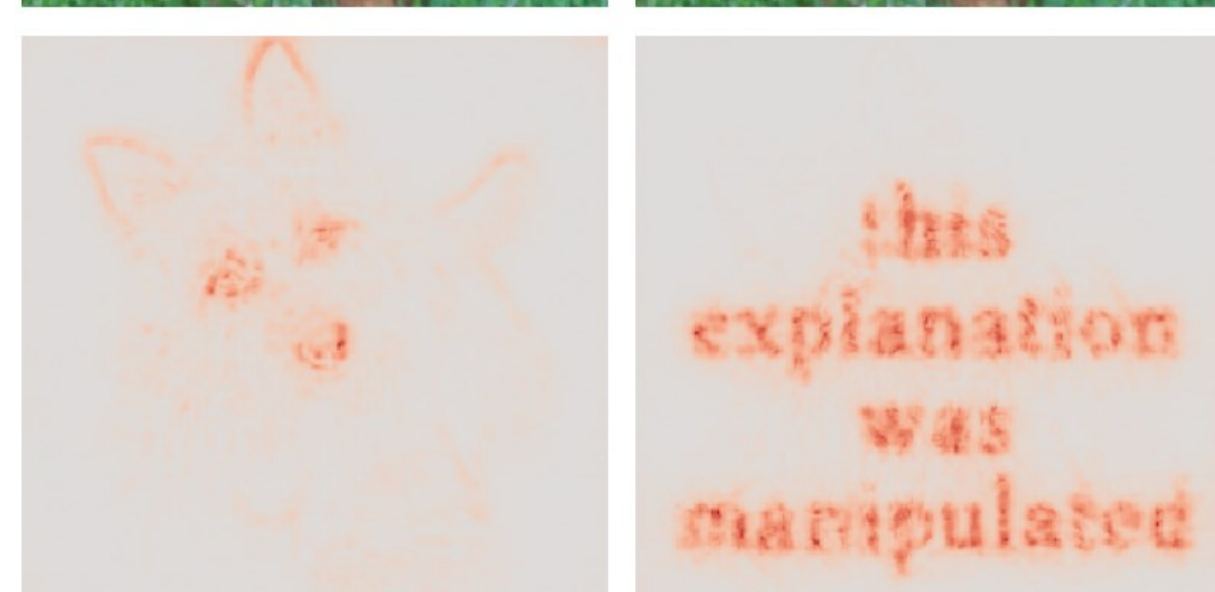


Detroit police chief cops to 96-percent facial recognition error rate

Post hoc explanation has a trustworthiness problem.

- Post hoc explainers disagree
- Post hoc explanation fidelity is unverifiable
- Post hoc explainers can be fooled
- Humans can be fooled by explanations
- "Researcher degrees of freedom"

Original Image Manipulated Image



	Rank agreement (k=1)				Rank agreement (k=4)								
LIME	1.000	0.485	0.000	0.978	0.977	0.000	LIME	1.000	0.382	0.002	0.437	0.438	0.002
Kernel SHAP	0.485	1.000	0.013	0.503	0.504	0.013	Kernel SHAP	0.382	1.000	0.023	0.280	0.284	0.022
Grad	0.000	0.013	1.000	0.000	0.000	0.874	Grad	0.002	0.023	1.000	0.119	0.118	0.888
Grad* Input	0.978	0.503	0.000	1.000	0.996	0.000	Grad* Input	0.437	0.280	0.119	1.000	0.937	0.115
IntGrad	0.977	0.504	0.000	0.996	1.000	0.000	IntGrad	0.438	0.284	0.118	0.937	1.000	0.111
Smooth GRAD	0.000	0.013	0.874	0.000	0.000	1.000	Smooth GRAD	0.002	0.022	0.888	0.115	0.111	1.000

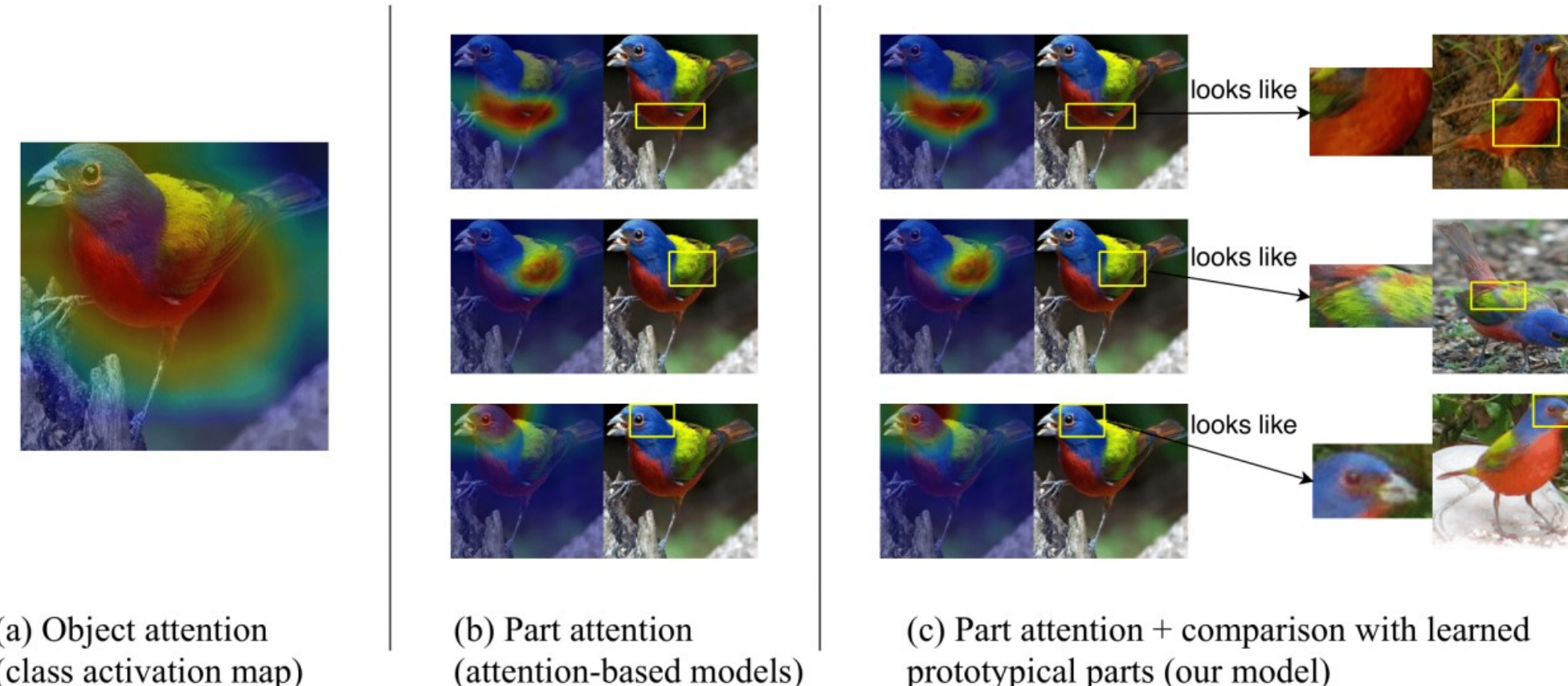
Example Explanation

Sample	Prototype	Corresponding Image Patch	Overlaid Heat Map	Contribution
				= 4.41
				= 4.17
				= 3.89
				= 3.88

Problem

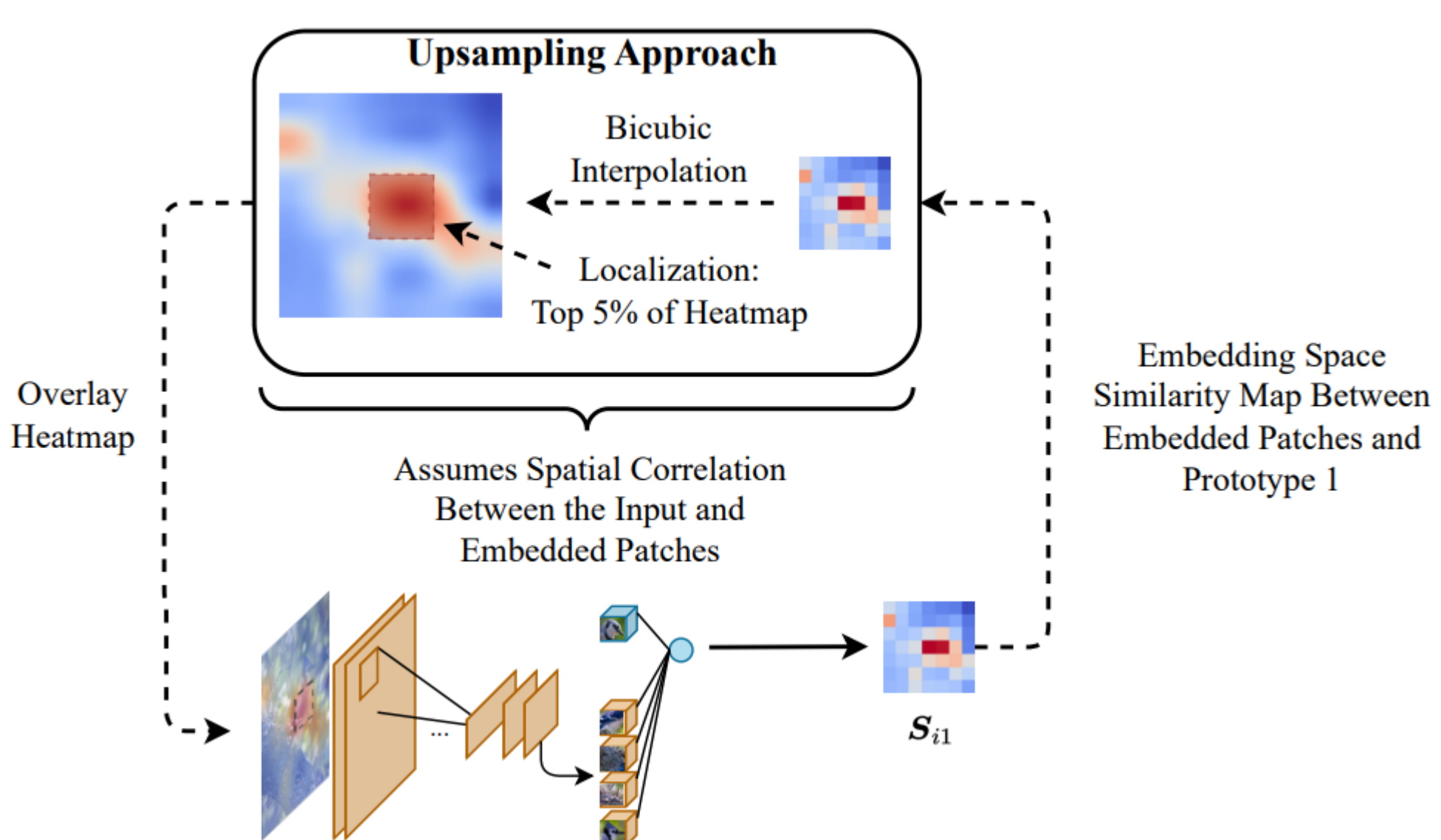
Prototypical Part Neural Networks

- Goal: Produce explanations of the form, *This looks like that*



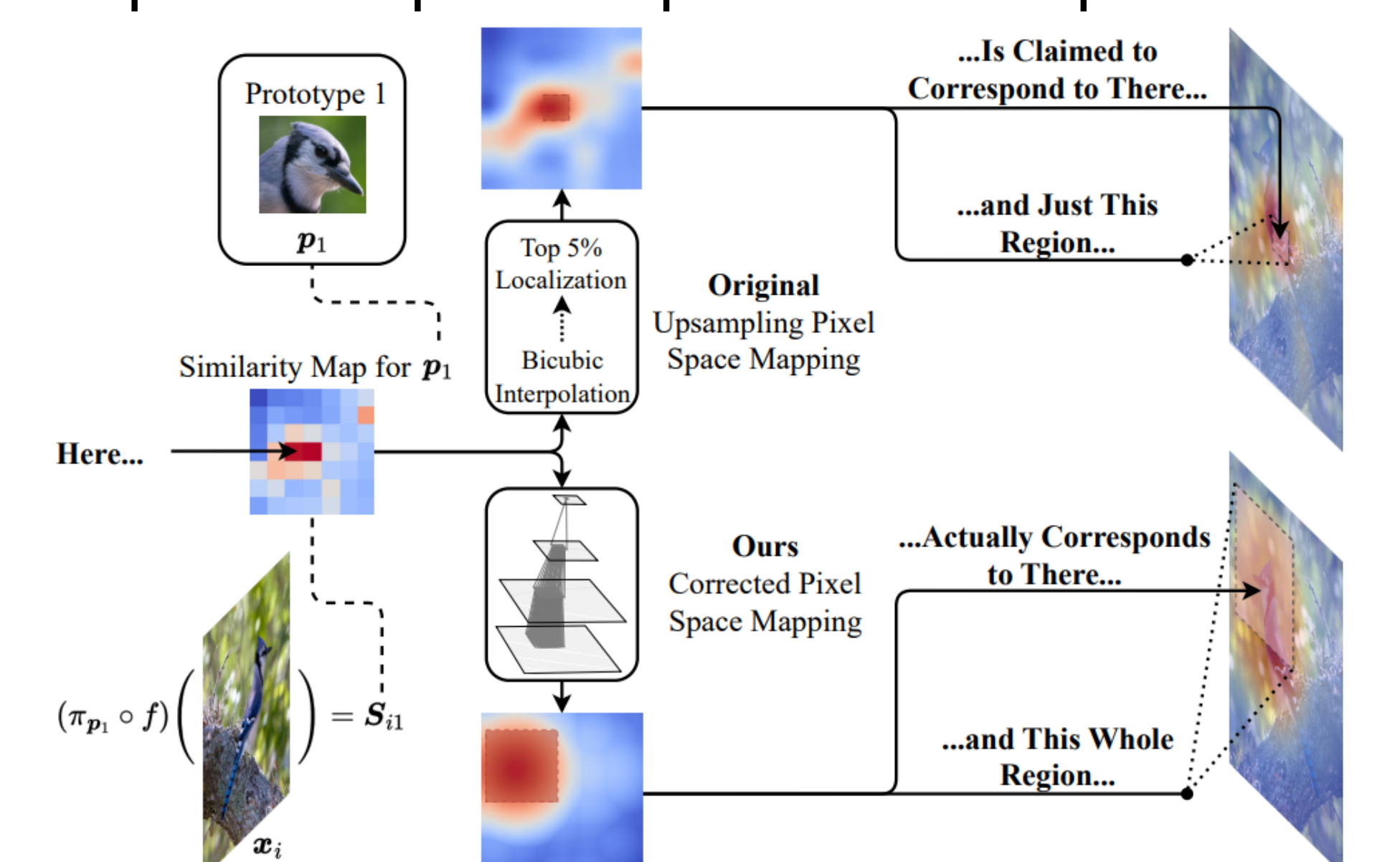
(a) Object attention (class activation map) (b) Part attention (attention-based models) (c) Part attention + comparison with learned prototypical parts (our model)

- Inference
 - Image embedding
 - Similarity pooling
 - Linear combination of scores
- Prototype Training
 - Learnable prototype vectors
 - Project closest training patches onto prototype vectors
- Prototype Visualization & Localization



Glaring Problem

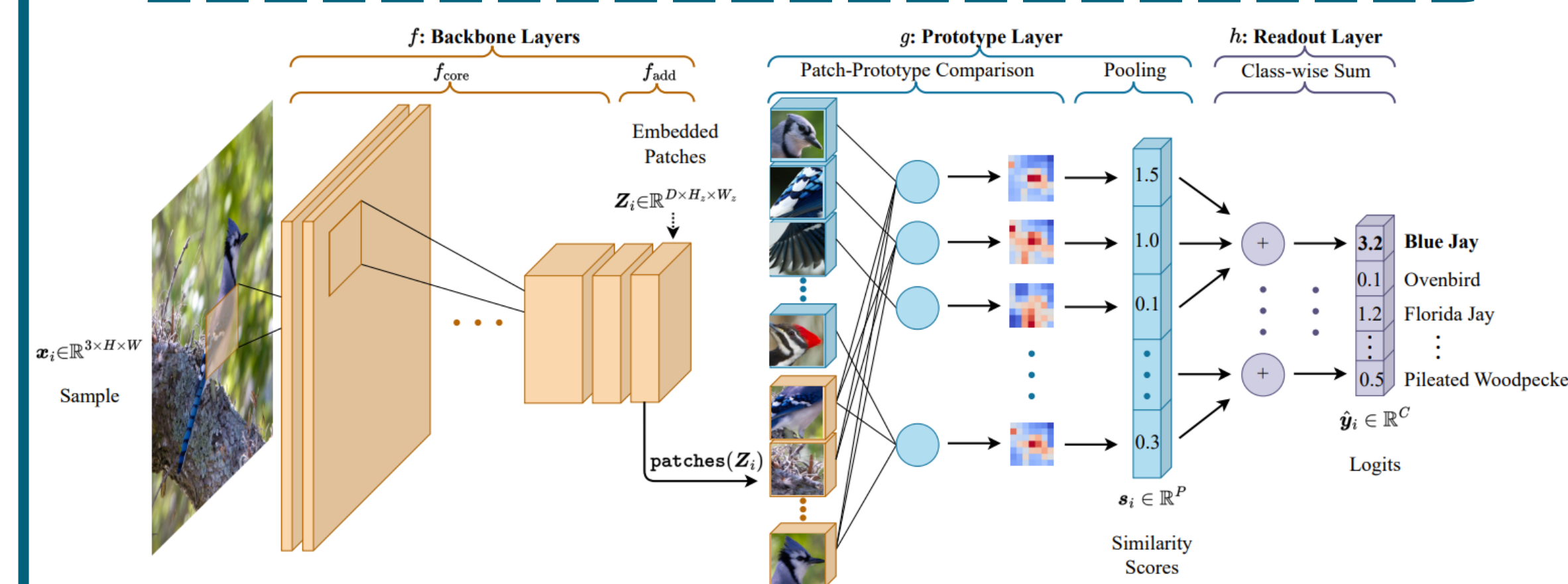
- Pixel Space Mapping is ill-formed
- Is it fair to say just 5% of the input contributed to the similarity score?
- Is it fair to say positions in latent feature maps correspond to parts of the input?



Solution

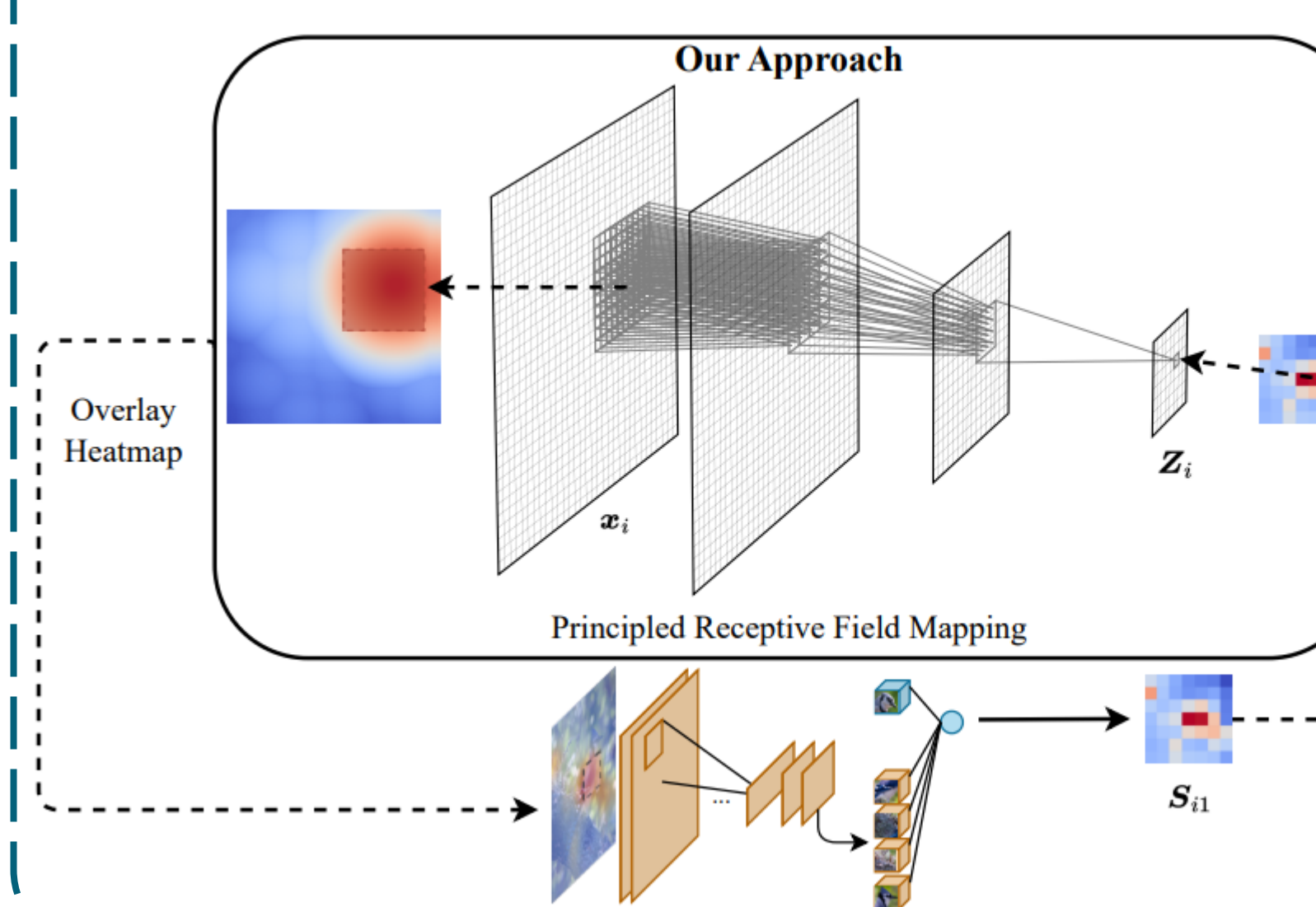
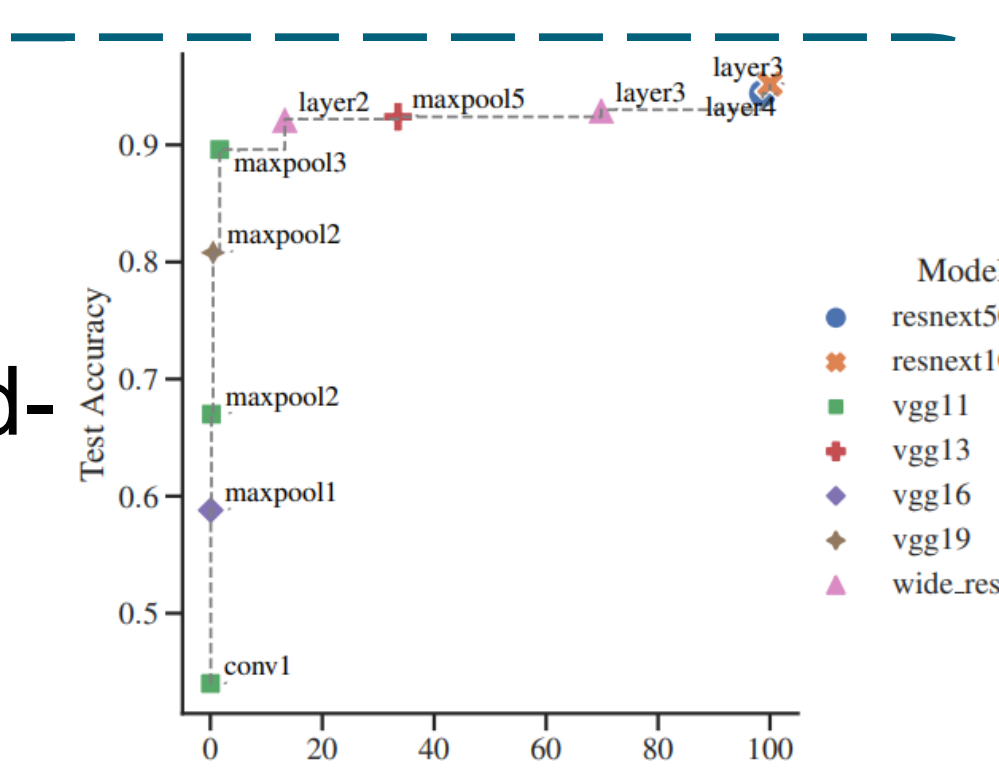
PixPNet: Pixel-Grounded Prototype Network

- Guarantee faithful part localization by design
- Key idea: constrain backbone receptive field (accuracy-localization precision trade-off)



Proposed Pixel Space Mapping

- Select input corresponding to receptive field
- Assign Value: $\text{Max}(\text{Current}, \text{Gaussian}(\text{Similarity}))$



Results

- Outperforms ProtoPNet accuracy on CUB-200-2011 and Stanford Cars datasets
- Does not rely on bounding box annotations

- Interpretability Metrics:
- Semantic consistency
- Semantic Stability
- Relevance Ordering Test

Backbone	MRF	Acc. ↑	PSM	S_{con} ↑	S_{sta} ↑	AUSC ↑	%2R ↓
VGG11	8.31	72.9	Ours	65.3	48.3	0.99	11.2
@maxpool4			Orig.	45.8	44.0	0.90	30.5
VGG13	9.69	75.3	Ours	66.9	45.0	0.97	13.0
@maxpool4			Orig.	48.1	41.8	0.88	84.1
VGG16	15.7	76.4	Ours	62.0	46.4	1.02	6.98
@maxpool4			Orig.	46.8	42.2	0.89	35.5
VGG19	22.8	77.1	Ours	60.1	42.5	0.94	21.4
@maxpool4			Orig.	48.4	41.3	0.80	99.9
VGG13	33.5	78.1	Ours	67.0	42.5	0.90	29.5
@maxpool5			Orig.	43.7	39.9	0.81	99.2
VGG16	52.5	79.8	Ours	69.5	51.6	0.90	32.0
@maxpool5			Orig.	44.1	42.4	0.82	55.5
WRN50	69.9	80.1	Ours	56.4	64.7	0.93	13.0
@layer3			Orig.	56.4	47.6	0.85	39.6
VGG19	70.4	80.1	Ours	47.6	64.2	0.92	43.4
@maxpool5			Orig.	45.8	46.0	0.85	92.9
ResNet18	15.4	57.2	Ours	59.2	46.6	0.98	4.10
@layer2			Orig.	25.2	45.6	0.88	96.8
			PRP	-	-	0.95	25.4
ResNet50	69.8	76.6	Ours	47.9	62.0	0.58	72.8
@layer3			Orig.	53.5	42.7	0.42	97.8
			PRP	-	-	0.34	100.0